# **Connecting to the 4m telescope VNC server**

• Connecting from the guest terminal

As the computers in the observer building are connected to the MPIfR internal network, one can simply access the VNC by entering

vncviewer 134.104.70.120:99

into a unix terminal and then entering the password.

A window should appear with the VNC desktop. This is the telescope control computer "4mteleskop".

• Connecting from outside the MPIfR network

You need to establish an SSH tunnel to the MPIfR servers. For this you need an MPIfR account. With this you need to log into username@portal.mpifr-bonn.mpg.de when establishing the tunnel. The port to then access display:99 is 5999.

For Windows *MobaXterm* has a VNC client and a tunneling option in a single program for convenience.

# Starting the telescope control programs

- 1. The clipboard is not shared with the VNC. Thus, it helps if you open the page containing the most important commands through a browser from within the VNC.
- 2. Open a terminal on: 4mteleskop
- 3. If not already there, go to the directory: /home/operateure/
- 4. If you want to specify different folders to save your spectroscopy and continuum data in, you can do so by editing /home/operateure/start4m.sh through any text editor.
- 5. Use the command: ./start4m.sh This should open all the necessary windows to operate the telescope.
- 6. Minimize or resize the windows you don't immediately need so the 4mcontrol.py window with the blue input line is visible. This is from where you can control the telescope.

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4mcontrol.py is the main interface to the telescope where one can enter commands.

skripttelcontrol4m.py makes the calculations for the telescope positioning and constantly returns imprecise values about where the telescope is pointing. The VLC Media Player window has a live feed from a webcam showing the telescope. The Regler window displays the datastream from the motors of the telescope. The windows with the data plots pop up automatically when a new batch of data is saved. datawriter.py writes the data for the continuum backend, while fftsdatwriter does the same for the FFTS backend. pbeControl displays data activity from the telescope.

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# **Preparing the measurement**

## • Continuum backend

The continuum backend measures the total flux coming from the telescope over the whole range of Frequencies received. It is usually used to quickly map out where radio sources are. It can be started by entering:

```
pbebackend('cmdusedchannels 1 1','cmdnumphases 1','cmdmode
external','configure')
```

### • FFTS backend

The Fast Fourier Transformer backend separates the signal from the telescope into its constituent frequencies. This allows the detection of physical processes radiating at distinct frequencies in specific regions of the sky. It can be started by entering:

```
fitwriter('band1:cmdnumspecchan 8192','band2:cmdnumspecchan
8192','cmdusedsections 1 1','cmdmode int','cmdsynctime 200000','cmdblanktime
2','cmdnumphases 1','configure')
```

### 1. Starting the observation

In both cases the selection of the backend must be followed up by

send()

to actually send the command through the network to the appropriate devices. After this you can start the observation by entering

```
start_messung()
```

# **Observing with the telescope**

# Limits

The telescope can only move within certain limits. These are:

Elevation	0°-90°
Azimuth	-70°-270°

Be careful not to let the telescope cross over these limits.

# **Observation Commands**

## • <u>Point</u>

In order to point the telescope towards a specific heading - for example when shutting it down - you can use the command:

```
set_position_azel(integration = 0, el = (posel,unitel), offsety =
  (offy,unitoffy), az = (posaz,unitaz), offsetx = (offx,unitoffx), velaz =
  None, velel = None)
```

The correct shutdown position is Elevation: 35, Azimuth: 130,

## • <u>Track</u>

In order to track an object across the sky, you can use the command:

```
track(messobjekt, integration = None, offsetx = (offx,unitoffx), offsety
=(offy,unitoffy))
```

## • <u>Crosscan</u>

To detect the maximum intensity and precise position of sources, you can use the command:

```
crossscan(integration,messobjekt = None, az = (posaz,unitaz), el =
(posel,unitel), lengthx = (lengthaz,unitlenx), lengthy = (lengthel,unitleny),
offsetx = (offx,unitoffx), offsety =(offy,unitoffy))
```

The speed at which the telescope moves is determined by the integration time given, and the length given for the crossscan. The telescope will move to approximately to "position - 1/2 length" and then sweep over to approximately "position + 1/2 length" over the time frame given. It adds a couple of seconds of movement at the beginning and the end to avoid sudden jolts of the telescope.

## <u>Calibration</u>

The calibration diode is used to give a reference flux to determine the actual signal strength by comparing the incoming signal to it. For the time being it has to be turned on and off manually at the start of each scan. It should only need to be turned on for a few seconds. This can be done via:

cal\_on()

and

cal\_off()

## <u>Multiple tasks</u>

Currently the only way to queue up multiple tasks is to write a separate short python script and execute it via the execfile("/path/name.py") command. Take care to space out your scans with time.sleep() to allow for the full integration time as well as telescope movement!

## • Example

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This was an azimuth crossscan over the Sun via crossscan(50000, "sun", lengthx=(14, 'd')), with both continuum and spectroscopy backends enabled.

# Variables

The commands for the telescope have several variables that you change for each command. If you leave out a variable, the control program will use the default value. (Mostly 0.)

Variable	Purpose	Default Value	Unit	Other
integration=None,	sets the time for collecting radio flux from the specified source	None=infinite	ms	0 means no data collected
offsetx=(offx,unitoffx),	sets an offset in azimuth to point beside the given coordinates	0, 0,	unitoffx with the format 'd' for degrees	can be used to fine tune pointing
offsety=(offy,unitoffy),	sets an offset in elevation to point beside the given coordinates	0, 0,	unitoffy in the format 'd' for degrees	can be used to fine tune pointing
velaz=None,	sets the velocity at which the telescope moves along the azimuth axis	'Schleichgang'	'Schleichgang': slow, 'Eilgang': fast, 1: 1°/sec	velocity is calculated automatically for crosscans
velel=None,	sets the velocity at which the telescope moves along the elevation axis	'Schleichgang'	'Schleichgang': slow, 'Eilgang': fast, 1: 1°/sec	velocity is calculated automatically for crosscans
coorsys = 'J2000.0',	specifies in reference to which point in time the coordinates were given	'J2000.0'	'J2000.0' OR 'B1950'	
lng = (l, unitl),	sets the longitude position of the telescope in galactic coordinates	0, 0,	unitl with the format 'd' for degrees	
br = (b, unitb),	sets the longitude position of the telescope in galactic coordinates	0, 0,	unitb with the format 'd' for degrees	

Variable	Purpose	Default Value	Unit	Other
ra = (rec, unitrec),	sets the right ascension position of the telescope in equatorial coordinates	0, 0,	unitrec with the format 'd' for degrees	
dec = (decl, unitdec),	sets the declination position of the telescope in equatorial coordinates	0, 0,	unitdec with the format 'd' for degrees	
el = (posel,unitel),	sets the elevation position of the telescope in local coordinates	0, 0,	unitel with the format 'd' for degrees	with this option the telescope does not turn with the rotation of the earth
az = (posaz,unitaz),	sets the azimuth position of the telescope in local coordinates	0, 0,	unitaz with the format 'd' for degrees	with this option the telescope does not turn with the rotation of the earth
messobjekt,	specifies which source to point towards	None	_	names looked up in in CDS name resolver
lengthx = (lengthaz,unitlenx),	specifies the distance the telescope should move in azimuth during a crossscan	0, 0,	unitoffx with the format 'd' for degrees	
lengthy = (lengthel,unitleny),	specifies the distance the telescope should move in elevation during a crossscan	0, 0,	unitoffy with the format 'd' for degrees	

# **Other commands**

get\_position()

Displays the current positioning of the telescope in az/el.

get\_status()

Displays whether or not the telescope is already pointing at the desired target.

# Bugs

### • Telescope not moving, not giving out data

This indicates that the telescope control programs froze for some reason and need to be restarted. Close all windows by pressing Ctrl+C or the X button on each of them. Restart the telescope control programs via ./start4m.sh.

### • Telescope still not moving, optionally giving error messages

If a crossscan was started close to the hardcoded Azimuth endpoints of the telescope, it is possible that the telescope crossed over this endpoint. This means the actuator controls will have to be manually restarted take a look at section Limit Position exceeded (F6029 Lagegrenzwert überschritten).

### • Multiple backends online at the same time, don't turn off on restart

This happens occasionally, and while the plotting windows can be a nuisance, the data is unaffected and measurements can continue normally.

### • 134.104.70.120:99 is not accepting the password

First the validity of the password needs to be checked. If it is still not allowing a connection the wrong password may have been entered too many times, in which case a technician will need to restart the VNC server to reset the lockout.

### • Connection error: control unit (F9100 Antriebsfehler)

#### **Open IndraWorks Ds:**

🛃 Verbindur				-	-	23
Netzwerk-Suc	he IP-Adress-Suche	Seriell Fremd	steuerung Offlir	ne		
Netzwerkad	apter: LAN-Verbind	ung		•		Suchen 💌
Adresse	Anwendungsart	Firmware	Serien-Nr.	IP-Adresse	Identifizieren	Verbinden
·	Einstellungen					Alle verbinden
						Keine verbinden
EtherCA	T/VARAN Deaktivieru	ng				
Verbindu	ngsauswahl beim Start	anzeigen			Ok	Abbrechen
Verbindu	ngadawan bein Statt	unzagen				

Search Units. If you can't found the units there are a hardware bug. Then you need to restart the hardware. (Heizungsraum Sicherung -30F1)

### After the restart search again:

Verbindu	ingsauswahl					<b>X</b>
Netzwerk-Su	che IP-Adress-Such	ne Seriell Fren	ndsteuerung Offline			
Netzwerka	dapter: LAN-Verbi	indung	•			Suchen 💌
Adresse	Anwendungsart	Firmware	Serien-Nr.	IP-Adresse	Identifizieren	Verbinden
1	default	MPB-20V13	7260407371735	134.104.79.88		<b>V</b>
2	default	MPB-20V13	7260406670991	134.104.79.89		<b>V</b>
						Alle verbinden
EtherC	Einstellungen	erung				keine verbinden
Verbind	ungsauswahl beim St	art anzeigen		(	Ok	Abbrechen

If you connect to the hardware, the following window appears. Select the unit.

### $(134.104.79.88 \rightarrow \text{Elevation})$

(134.104.79.89	→ Azimut)
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🚰 IndraWorks Ds - Achsstatus - Achse [1] default					
Parametrierung Inbetriebnahme Diagnose Serv	ice Extras Hilfe				
🕲 Zuri 🕶 🐨 👻 🐟 🔻 👻 📊 👘 🏠 🙀 🔜	🍳 🛃 🛛 Steuer- und	💶 🌚 😵 🖳 🗕 🔀 🍰 🖪 🚥 💷	ی 🔁 😒	0	
LindraDrive [1] (134.104.79.88)	Achsnummer	Achsbezeichnung		Adresse	Achstyp
IndraDrive [1] (134.104.79.88) IndraDrive (134.104.79.89)	1	default		1	Reale Achse
IndraDrive [1] default					
Prickeungskommunikation	Achsstatus	A0012 Steuer- und Leistungsteil betriebs	bereit	ا 🕲	Fehler löschen
Leistungsversorgung     Achse [1] default	Aktuelle Werte				
Hungskommunikation - Achse	Position	-59 2334 mm			
🗈 🛅 Motor, Antriebsmechanik, Messsysteme	Geschwindigkeit	0,000 mm/min			
Grenzwerte					
ia	Beschleunigung	0,000 mm/s <sup>2</sup>			
Eelereaktion	Drehmoment / Kraf	t 0,0 %			Details <<
Messtaster					Dotaila
Optimierung / Inbetriebnahme     Lokale I/O	Motion		Status		
er-to Dokale I/O er-to Remote I/O		Nicht aktiv	<ul> <li>Steuer-ur</li> <li>Antrieb m</li> </ul>	omentenbehaftet ALT aktiv (AH)	etriebsbereit (Ab)
	Meldungen				
	🔵 n_ist = 0	🔵 P >= Px	🔵 In-Position	n	
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	Landstream		O negative	Dienmomentbegi	enzung
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	Geber 1	-59,2334 mm 🌖 in Referenz			
	Geber 2	0,0000 mm 🔾 in Referenz			
	Achse in Refere	nz			

This example shows the bug: Referenzverlust Geber 1.

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draDrive (134.104.79.89)	Achsnummer	Achsbezeichnung		Adresse Achstyp
IndraDrive [2] default	2	default		2 Reale Achs
<ul> <li>Leistungsversorgung</li> <li>Achse [2] default</li> </ul>	Achsstatus Aktuelle Werte	F2174 Referenzverlust Geber 1		Fehler löschen
-      -      Führungskommunikation - Achse     -      Motor, Antriebsmechanik, Messsysteme     -      Grenzwerte	Position	160,0000 Grad		
	Geschwindigkeit	0,0000 U/min		
Betriebsarten / Antrieb Halt     Betriebsarten / Antrieb Halt	Beschleunigung	0,000 rad/s <sup>2</sup>		
Messtaster     Optimierung / Inbetriebnahme	Drehmoment / Kraft	-0.4 %		Details <<
Cokale I/O	Motion		Status	ahahamit (hh)
		Nicht aktiv	<ul> <li>Steuer- und Le</li> <li>Antrich memer</li> <li>Antrich HALT</li> </ul>	istungsteil betriebsbereit (Ab) tenbehaftet (AF)
	Meldungen		🕘 Antriebsfehler	
	<ul> <li>n_ist = 0</li> <li>n_ist &lt; nx</li> <li>n_ist = n_soll</li> </ul>	<ul> <li>P &gt;= Px</li> <li>Md &gt;= Mdx</li> <li>Md &gt;= Mdgrenz</li> </ul>	<ul> <li>In-Position</li> <li>In-Positionsfen</li> <li>positive Drehm</li> <li>negative Dreh</li> </ul>	
	Lageistwerte			
	Geber 1	160,0000 Grad 🔾 in Referenz		

You need to set a new reference. Write to "Referenzmaß" the value of "Aktueller Lageistwert". Then reset the bug.

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L			1	

Push the button "Absolutmaß setzen"

Now the units should work.

#### Attention:

Both Achsstatus must show "A0012 Steuer- und Leistungsteil betriebsbereit". In addition it's only possible to communicate with the IndraWorks Ds <u>or</u> with the Controlsystem. If you want to control the teleskop with the Controlprogram you need do close IndraWorks Ds.

### • Limit Position exceeded (F6029 Lagegrenzwert überschritten)

Open IndraWorks Ds and search the units. **<u>Attention</u>**: You need to close the controlsystem, because it's only possible to communicate with Indraworks <u>or</u> the controlsystem.

Choose the unit:

 $(134.104.79.88 \rightarrow \text{Elevation})$ 

 $(134.104.79.89 \rightarrow Azimut)$ 

Delete the error. After deleting the error the Achsstatus should show "A0012 Steuer- und Leistungsteil betriebsbereit".

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Push "Start Easy-Startup-Modus" and "Freigabe".

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Attention: Now you drive without any position limits!! Take care that you drive in the correct

## direction!!

If the telescope is out of the position limit press the button "Antrieb AUS" and then "Stop Easy-Startup-Modus". The Achsstatus must show "A0012 Steuer- und Leistungsteil betriebsbereit".

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Close IndraWorks and open the controlsystem. Now the program should run.

### Other Error

If the telescope does not function due to a different error, you should contact a technician.

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